

Ultrasonic sensor UC2000-F43-2KIR2-V17

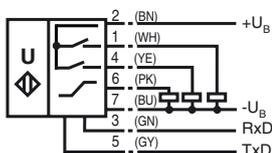


Features

- Current output 4 mA ... 20 mA
- 2 relay outputs
- Serial interface
- Temperature compensation
- Reverse polarity protection
- Parameterisable with ULTRA 2001

Electrical connection

Standard symbol/Connection:

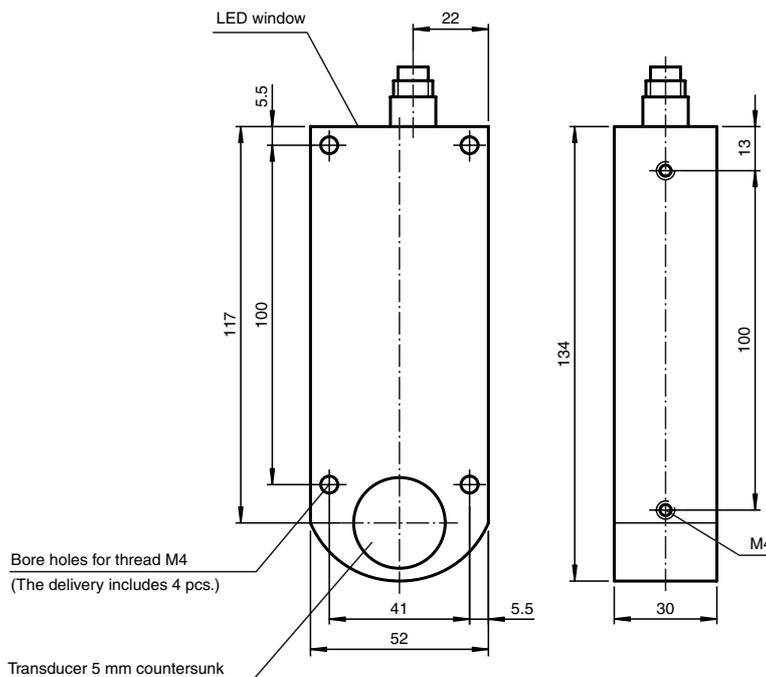


Core colours in accordance with EN 60947-5-2.

Connector V17



Dimensions



Bore holes for thread M4
(The delivery includes 4 pcs.)

Transducer 5 mm countersunk

Technical data



General specifications

Sensing range	80 ... 2000 mm
Adjustment range	100 ... 2000 mm
Unusable area	0 ... 80 mm
Standard target plate	100 mm x 100 mm
Transducer frequency	approx. 175 kHz
Response delay	minimum (EM; NONE): ≤50 ms (2 measuring cycles) factory setting (EM; MXN, 5, 2): ≤150 ms (6 measuring cycles) dynamic (EM; DYN): ≤75 ms (3 measuring cycles)

Indicators/operating means

LED green	continuous: object in the measuring window flashing: object outside the measuring window error (e. g. interference level too high)
LED red	

Electrical specifications

Operating voltage	10 ... 30 V DC ripple ± 10 % _{SS}
Power consumption P ₀	≤ 2 W (all relays pulled-in, current output 20 mA) no-load power consumption ≤ 0.7 W
Interface	
Interface type	RS 232, 9600 bit/s, no parity, 8 data bits, 1 stop bit
Output	
Output type	2 relay outputs, 1 analogue output 4 ... 20 mA
Resolution	0.6 mm
Deviation of the characteristic curve	< 0.2 % of full-scale value
Repeat accuracy	≤ 0.1 % of full-scale value
Range hysteresis H	0 ... 15 % parameterisable with ULTRA 2001
Load impedance	current output: ≤ 500 Ω at U _B ≥ 17V ≤ 200 Ω at U _B < 17V
Contact loading	60 V DC / 1 A (max. 24 W DC), ohmic
Lifetime	electrical: 3 x 10 ⁵ switching cycles at resistive load (1 A / 24 V DC) mechanical: 10 ⁷ switching cycles
Temperature influence	≤ 2 % of full-scale value

Standard conformity

Standards EN 60947-5-2

Ambient conditions

Ambient temperature	-25 ... 70 °C (248 ... 343 K)
Storage temperature	-40 ... 85 °C (233 ... 358 K)

Mechanical specifications

Protection degree	IP65
Connection	8-pin round connector, Lumberg type RSF 8
Material	
Housing	PBT
Transducer	epoxy resin/hollow glass sphere mixture; polyurethane foam
Mass	290 g

Notes

Thanks to its extensive command set, the sensor can be configured to suit the application via the RS 232 interface.

RS 232 command set (overview)

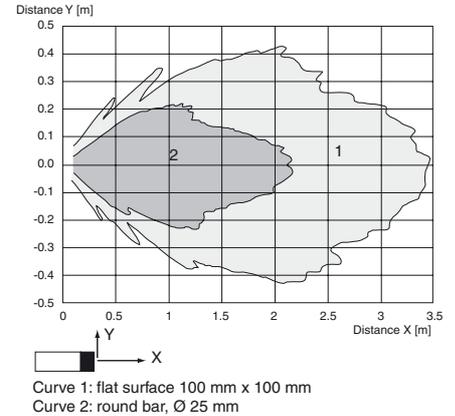
Command	Meaning	Parameter	Access
VS0	Velocity of Sound at 0 °C	Velocity of sound at 0 °centigrade VS0 in [cm/s] {12000 ... 60000}	read and set
VS	Velocity of Sound	Velocity of sound VS in [cm/s]	read
TO	Temperature Offset	TO in [0.1K]	read and set
TEM	TEMperature	TEM in [0.1K]	read and adapt to TO
REF	REFerence measurement	REF distance in [mm] {100 ... 4000}	adaptation of VS0
SD1	Switching Distance 1	Switching point, relay 1 SD1 in [mm] {100 ... 4000}	read and set
SD2	Switching Distance 2	Switching point, relay 2 SD1 in [mm] {100 ... 4000}	read and set
SH1	Switching Hysteresis 1	Hysteresis, relay 1 in [%] {0 ... 15}	read and set
SH2	Switching Hysteresis 2	Hysteresis, relay 2 in [%] {0 ... 15}	read and set
NDE	Near Distance of Evaluation	Near measuring window limit in [mm] {100 ... 4000}	read and set
FDE	Far Distance of Evaluation	Far measuring window limit in [mm] {100 ... 4000}	read and set
BR	Unusable area (Blind Range)	Unusable area in [mm] {0 ... 4000}	read and set
RR	Range Reduction	reduces sensing range [in mm] {100 ... 4000}	read and set
CBT	Constant Burst Time	Burst length {0,1, 2, 3}	read and set
CCT	Constant Cycle Time	Time in [ms] {0 ... 1000}	read and set
FTO	Filter TimeOut	Number of measurements without echo to be filtered {0 ... 255}	read and set
EM	Evaluation Method	Evaluation method { 0 = NONE; PT1[<i>f,p,c</i>]; MXN[<i>m,n</i>]; DYN[<i>p</i>] }	read and set
CON	CONservative filter	Counter threshold as number {0 ... 255}	read and set
OM	Output Mode	OM coded [normally-open = 0, normally-closed = 1, inactive = I]	read and set
FSF	Fail Safe Function	Failure function type e.g. FSF,11,35 {0,1,2}, [fault current in 0.1 mA], -1 = current output indifferently	read and set
MD	Master Device	Function as master {0 = NONE},AD,RD,RT,SS,ADB,RDB,RTB }	read and set
MA	Main Application	Determines whether the green LED orients on analogue output or switching outputs {A,S}	read and set
NEF	No Echo Failure	Sensor behaviour when no echo is present {0,1}	read and set
AD	Absolute Distance	Distance in [mm]	read
RD	Relative Distance	Relative distance as number {0 ... 4095}	read
RT	RunTime	Echo run time in machine cycles [1 machine cycle = 1.085µs]	read
SS1	Switching State 1	SS1 binary [0: inactive, 1 active] (independent of OM)	read
SS2	Switching State 2	SS2 binary [0: inactive, 1 active] (independent of OM)	read
ADB	Absolute Distance Binary	Distance in [mm] not as ASCII	read
RDB	Relative Distance Binary	Relative distance as number {0 ... 4095} not as ASCII	read
RTB	RunTime Binary	Echo run time in machine cycles [1 machine cycle = 1.085µs] not as ASCII	read
ER	Echo Received	Echo detected: no, yes [0/1]	read
VER	VERsion	Version string: xxxx	read
ID	IDentification	ID string: P&F UC2000-F43-2KIR2-V17...	read
DAT	DATE	Date string: e.g. Date: 04/12/02 Time: 11:14:35	read
ST	STatus	Status as hexadecimal string	read
RST	ReSeT	Performs a reset	Command
DEF	DEFault settings	Restores defaults	Command
SUC	Store User Configuration	Stores all settings	Command
RUC	Recall User Configuration	Restores stored settings	Command

Model number

UC2000-F43-2KIR2-V17

Characteristic curves/additional information

Characteristic response curve



Basic setting

OM:

Relay 1: NO
Relay 2: NO

SD1/SD2:

Switch point relay 1 = 100 mm
Switch point relay 2 = 2000 mm

NDE/FDE:

Analogue output: 4 mA ⇒ 100 mm
20 mA ⇒ 2000 mm

FSF:

Error ⇒ Relay 1 and 2: latest state
⇒ Analogue output: I_{out} = 3,9 mA

NEF:

No echo ⇒ error message

MA,S:

Switching mode

Accessories

RS 232 interface

UC-F43-R2

Service program

ULTRA 2001

Cable sockets *)

V17-G-2M-PUR

V17-G-5M-PUR

*) For additional cable sockets see section „Accessories“.